

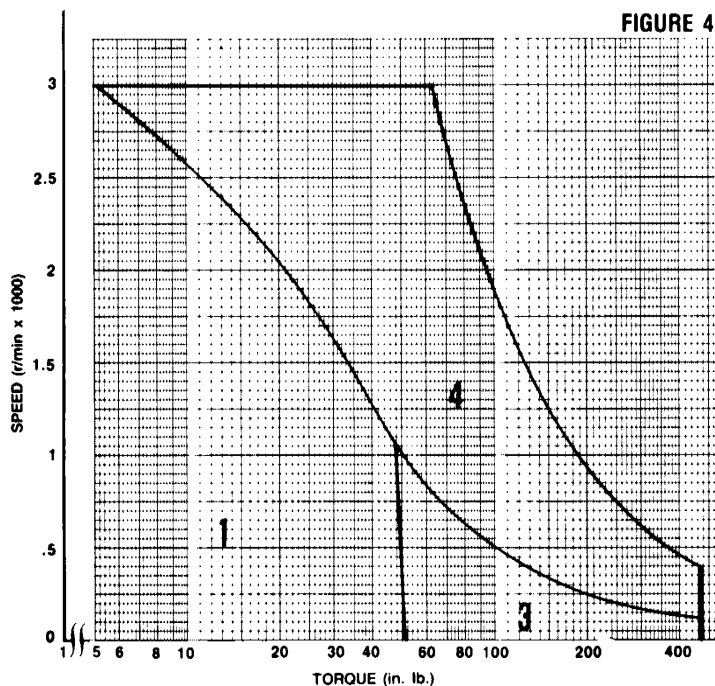
Motor Specifications

| Typical at 25°C | | | 4" Diameter Motors | | | 5 1/2" Diameter Motors | | | | | |
|---|-----------------------|------------------------|--------------------|-------|-------|------------------------|-------|-------|-------|-------|-------|
| | Symbol | Unit | M111 | M112 | M113 | M121 | M122 | M123 | M124 | M125 | M126 |
| Operating Parameters | | | | | | | | | | | |
| Continuous Rated Torque at stall (TENV) | T_s | lb-in | 16 | 25 | 36 | 51 | 53 | 83 | 87 | 104 | 110 |
| Continuous Rated RMS Current at Stall (TENV) | I_c | ampere | 5.6 | 8.6 | 12.5 | 12 | 21 | 12 | 21 | 12 | 21 |
| Maximum Winding Temperature by Resistance | Θ_a | °C | 155 | 155 | 155 | 195 | 195 | 195 | 195 | 195 | 195 |
| Absolute Maximum Peak Current before Demagnetization | I_m | ampere | 40 | 48 | 70 | 120 | 210 | 120 | 210 | 120 | 210 |
| Mechanical Parameters | | | | | | | | | | | |
| Rotor Inertia | J_m | lb-in-sec ² | .010 | .013 | .020 | .045 | .045 | .060 | .060 | .080 | .080 |
| Maximum Theoretical Acceleration at Stall | $\ddot{\Theta}_{max}$ | rad/sec ² | 10375 | 9773 | 9103 | 10152 | 10668 | 12474 | 13045 | 11759 | 12380 |
| Mechanical Time Constant | t_m | second | .014 | .013 | .014 | .011 | .011 | .009 | .01 | .009 | .01 |
| Thermal Time Constant | t | minute | 50 | 50 | 55 | 60 | 60 | 90 | 90 | 95 | 95 |
| Static Friction | T_f | lb-in | 1 | 1.25 | 1.5 | 2 | 2 | 2 | 2 | 2 | 2 |
| Weight | | lb | 12.3 | 14.0 | 18.9 | 42 | 42 | 55 | 55 | 70 | 70 |
| Electrical Parameters | | | | | | | | | | | |
| Back EMF Constant ±10% | K_e | v/1000 r/min | 34.1 | 34.8 | 34.2 | 50 | 30 | 82 | 49 | 103 | 62 |
| | K_v | v-sec/rad | .325 | .332 | .326 | .48 | .29 | .78 | .47 | .98 | .59 |
| Torque Constant ±10% | K_t | lb-in/amp | 2.88 | 2.94 | 2.89 | 4.23 | 2.54 | 6.93 | 4.14 | 8.71 | 5.24 |
| Armature DC Resistance: (less brushes) ±10% (including brushes) | R_a | Ohm | 1.045 | .840 | .548 | .48 | .18 | .69 | .26 | .90 | .34 |
| | R_m | | 1.313 | 1.010 | .668 | .61 | .25 | .82 | .33 | 1.03 | .41 |
| Armature Inductance | L_a | mH | 3.5 | 3.0 | 2.2 | 1.9 | .70 | 3.1 | 1.1 | 4.7 | 1.7 |
| Electrical Time Constant | t_e | ms | 2.7 | .29 | 3.2 | 3.1 | 2.9 | 3.8 | 3.3 | 4.6 | 4.1 |
| Viscous Damping Coefficient (Zero Z Source) | F_o | lb-in-sec/rad | .715 | .966 | 1.410 | 3.33 | 2.95 | 6.59 | 5.85 | 8.29 | 7.54 |

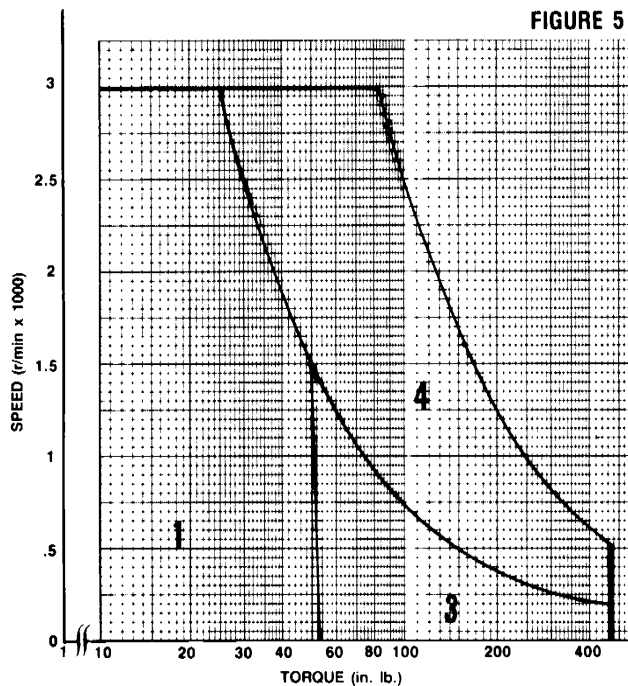
* This data is intended to aid you in making motor application decisions. Should you desire assistance in interpretation of data, please consult a Gettys application specialist.

Motor Performance Information*

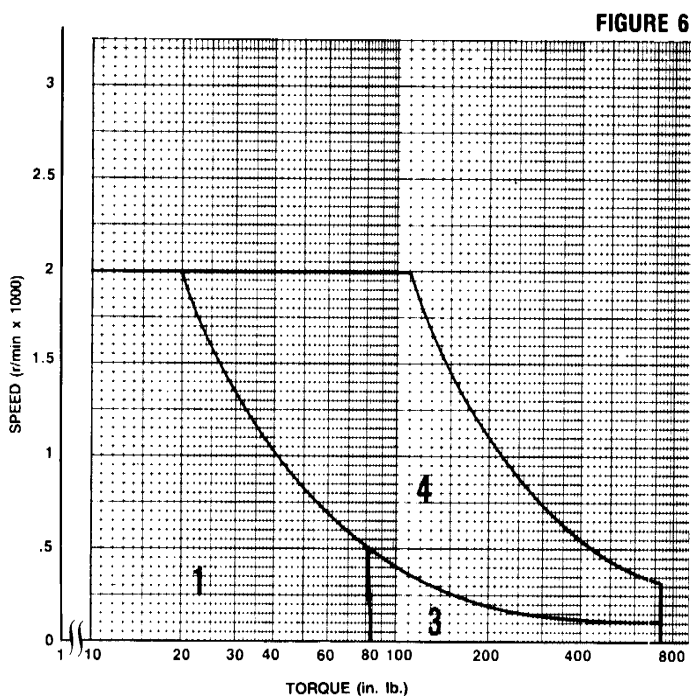
D.C. OPERATION FOR M121 MOTOR



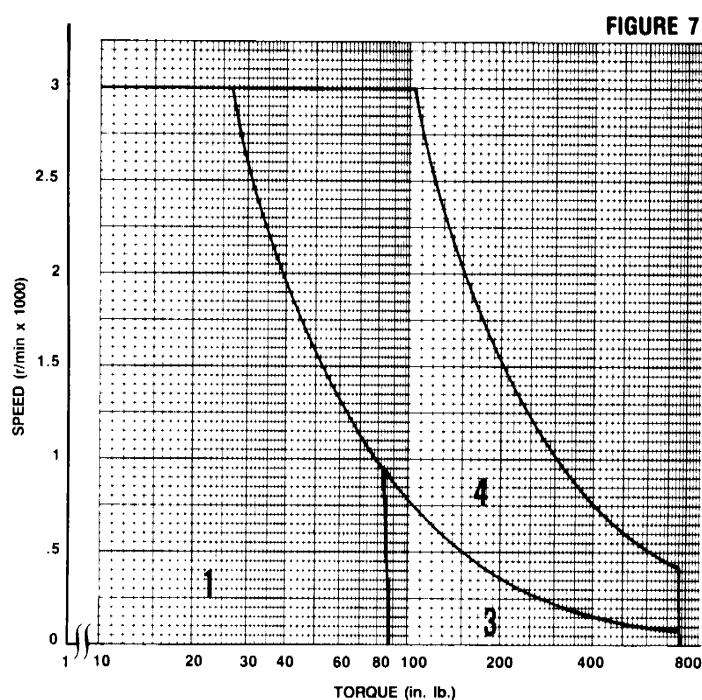
D.C. OPERATION FOR M122 MOTOR



D.C. OPERATION FOR M123 MOTOR



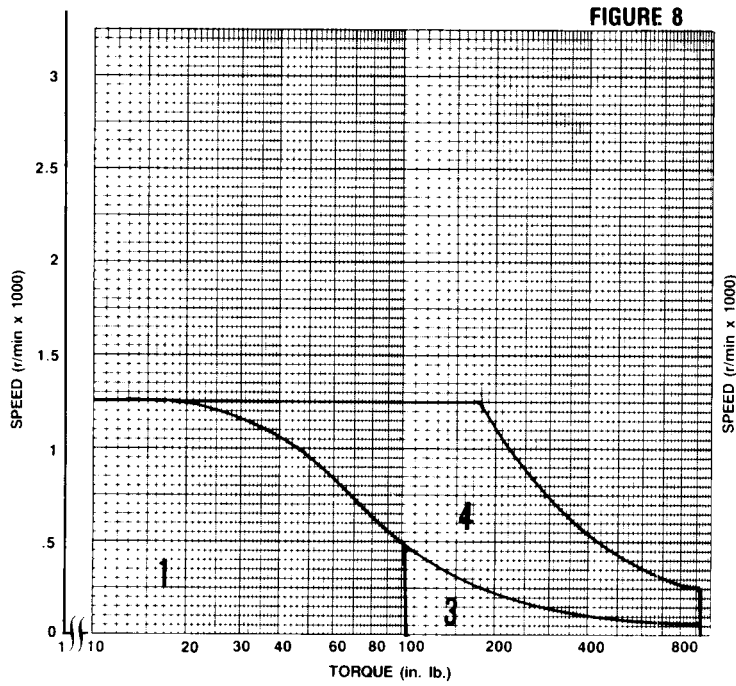
D.C. OPERATION FOR M124 MOTOR



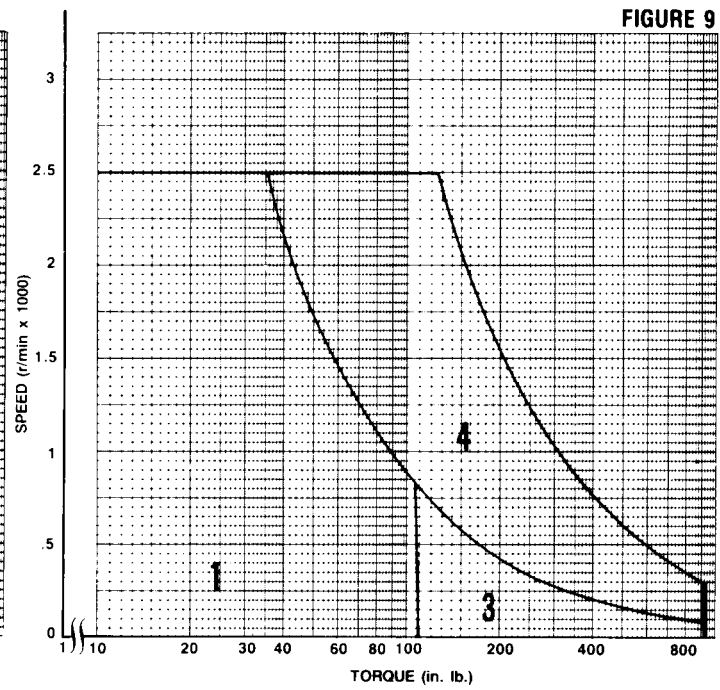
* Information provided is for DC operation at 25°C. (Motors M111-M113 have a 130°C rise; all other motors have a 155°C rise.) Motor performance information is based on 1.0 form factor; speed and torque figures must be derated by actual form factor of the amplifier used.

Motor Performance Information*

D.C. OPERATION FOR
M125 MOTOR



D.C. OPERATION FOR
M126 MOTOR



* Information provided is for DC operation at 25°C. (Motors M111-M113 have a 130°C rise, all other motors have a 155°C rise.) Motor performance information is based on 1.0 form factor; speed and torque figures must be derated by actual form factor of the amplifier used.